Full-scale wind lidar measurements of the shelter behind a fence Alfredo Peña^{1(*)}, Andreas Bechmann¹, Davide Conti¹, Nikolas Angelou¹, Torben Mikkelsen¹ and Peggy Friis¹

¹Wind Energy Department, Technical University of Denmark, Risø campus, Roskilde, DK

Introduction

The shelter behind obstacles is one of the most complex flows to measure and to model and so its study is important in applications such as wind energy. However, during the exponential-growth period of the wind industry, the shelter did not significantly represent an issue for turbine energy-yield estimation because the machines were sited in free-shelter regions. Currently, due to the less available 'best' wind sites, many turbines are deployed close to obstacles. Also the small wind industry has grown and in some countries, due to planning rules, small wind turbines are placed very close to houses, representing an increase of the sheltering effects. Here we present a dataset of full-scale measurements of the shelter behind a 3-m tall and 30-m wide solid fence, which were performed at DTU's Risø campus in Roskilde, Denmark. The measurements were conducted by the short-range WindScanner (WS) system (http://www.windscanner.dk), where three synchronized wind lidars measured the 3D wind velocity vector on a vertical-plane grid behind the fence. The measurements represent a wide variety of atmospheric conditions, and different cases are analyzed as function of the relative direction of the fence to the inflow. These cases present a unique opportunity to evaluate shelter models.









Figure 1: The fence experiment (left) on the area surrounding DTU's test station, (middle) with the instrumentation including the lidars and the mast, and (right) scanning configuration

Methods and inflow conditions

The shelter is shown in terms of the speed up, $U(z)/U_o(z)$, where the subscript o is the inflow value. The inflow characteristics are estimated using the diabatic wind profile,

$$U_o(z) = \frac{u_*}{\kappa} \left[\ln\left(\frac{z}{z_o}\right) - \phi_m(z/L) \right].$$
(1)

The cases represent the average shelter over direction intervals centered at three increasing relative directions θ s:

Shelter results

The WS scanned on a vertical plane at 7 levels following the terrain. Figure 3 shows the speed up for each case; although θ is not uniformly distributed, the differences in the shelter behavior are clear when varying the centered θ value. Case I shows the deepest effect of the fence on the flow and for case IV the fence is only 'noticed' within $x/h \lesssim 3$, where h is the fence height. Case III shows a region with a speed-up 'jump' at $x/h \approx 2.5$ and $z/h \approx 2.5$. Such 'jump' is also found in simulations performed with a RANS-type CFD model (not shown) and is due to increased vertical veloc-

	Case	heta [deg.]	<i>z_o</i> [m]	$u_* [{ m m \ s^{-1}}]$	z/L	No. of full scans
-		0 ± 15	0.0016	0.36	0.021	159
	111	-30 ± 15	0.0037	0.34	0.023	604
	IV	-60 ± 15	0.0131	0.39	0.045	583

The roughness length z_o is estimated from Eq. 1 using one month of 10min statistics from sonics at 6 and 12 m on the mast besides the fence (Fig. 1-right) and a median z_o is computed within 10° intervals. z_o in the table is the ensemble average of the 6-m derived z_o medians within the corresponding θ intervals of each case. The friction velocity u_* in the table is estimated from Eq. 1 assuming $\psi_m = 0$ and using the ensemble-average 6-m sonic mean wind, which is computed within the period of each WS full-scan (i.e. a complete measurement at all scanning positions on the grid in Fig. 1-right) and ensemble-averaged for the full-scans belonging to each case. The inflow profile estimated using Eq. 1 with $\psi_m = 0$ shows good agreement with the two sonics (not shown). The table includes the ensemble-average z/L found by averaging the 10-min 6-m sonic fluxes concurrent with the full-scans. Figure 2 shows an intercomparison of U measured by the 6-m sonic and the WS scanning grid point closest to the fence and at $z \approx 6$ m, and the difference between these two measurements as function of θ . The figure illustrates that the sonic and the WS agree well for the directions when the fence is in downwind conditions.

ity shear in that region (a 'positive' effect of the fence on the wind). Case IV shows that $U(z)/U_o(z) \approx 1$ for $x/h \gtrsim 4$, which indicates that there is a little effect of the topography on the flow at all scanning positions on the vertical plane compared to that at the mast position. Figure 3 also shows the direction and magnitude of the longitudinal velocity component measured by the WS. A region of reverse flow is visible below the shelter 'bubble' with the lowest speed ups. The magnitude of the reverse flow close to the fence, for case IV in particular, can be larger than the inflow value at the same vertical level. Preliminary comparisons with results from RANS-CFD and engineering obstacle models, such as that in WAsP (www.wasp.dk), reveal good agreement in the far wake (x/h > 6) and the need to include the distribution of θ in the model results.





Figure 2: Sonic and WS wind speed intercomparison

Figure 3: Speed up $U(z)/U_o(z)$ on the vertical plane behind the fence

http://www.vindenergi.dtu.dk

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